

# NEXVISION'S PRODUCTS ECOSYSTEM DEFENSE & SECURITY





Hello all.

This catalog of optronic products is the fruit of passionate and exciting R & D work.

It represents today's ecosystem of comprehensive products in the sectors of defense, civil security and aeronautics, with a driving force in «situational awareness», which is to say, in the mixing of technologies in order to understand a situational environment in real-time wherever it may be (ground, sky, air, water, fog, night, snow, sand, wind etc.).

This is a need found in all types of autonomous vehicles (drones, robots, cars etc.), in civil security and obviously in the military, where the armed forces call for a technological advantage to win battles on the ground.

Nexvision puts all its know-how into these technically advanced, state of the art products. Our team of engineers pushes the limits on a daily basis to find breakthrough solutions for clients seeking solutions in their respective markets.

As master craftsmen in optronics, we produce small series products, made to measure, without any concession to quality.

You will find this scrupulous attention to detail in all our products.

Vincent Carrier. CEO Nexvision



# **SUMMARY**

























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# ABOUT NEXVISION

# A GLOBAL EXPERTISE ON THE WHOLE VISION SYSTEM CHAIN AND A SHORT INTEGRATION PROCESS OF LATEST TECHNOLOGIES!

NEXVISION is an independant, innovative and successfull design house for electro-optics systems.

Exploration of new technologies is our DNA, and we integrate the entire design and integration scheme in our core activity.







**AEROSPACE** 



INDUSTRIAL INSPECTION



**MEDICAL** 

# **NEXVISION AT A GLANCE**

- A team of **30** engineers
- 16 years of existence and innovation
- **6** expertise pools : electronics, logic design on FPGA, optics, mechanics, embedded software & computer vision
- 25 core technical expertises
- A presence in 4 continents (North America, Europe, Africa, Asia)

# A global integrated expertise on the whole electro-optic vision systems chain:

From FPGA electronic design to mechanical and optical design along with embedded vision software, NEXVISION covers all technics with an agile team able to integrate a transversal expertise in a global approach.

# Early adopter for Nvidia embedded processors, Microoled displays and Photonis image sensors:

NEXVISION is one of the rare companies in the world to get an official technical support of Nvidia's Tegra media-processors (K1, X1, etc.) and of Photonis's new image sensors (SCMOS, EBCMOS, iCMOS).

# A large spectrum of technological survey:

NEXVISION is able to identify world technical innovations in vision applications from new components, algorithms, publications and concepts and react quickly to integrate new technologies to its expertise pool.

# A technology explorer:

NEXVISION's DNA is to test non-mature technology every time it is possible and to assess their potential. We learn how to master it to be able to propose them to our clients without any risk (Terahertz, LiDaR, SLAM, Fusion, HMC Memory, NVMe, EBCMOS imaging, OLED display, range gating...)

# A permanent support for our clients' technical key issues:

Research with our customers to identify their root needs and the best appropriated integrated solution. We go beyond the business mode of a design house by bringing to our customers our global optronic approach to their specific needs.

# A high reactivity level of experts:

With the integration of all expertise in a human sized organization, our teams are able to find a solution quickly and efficiently.

# **KEY PARTNERS**















# **OUR DESIGN HOUSE**

# YOUR BEST PARTNER TO DESIGN HIGH-FND INNOVATIVE VISION SYSTEMS

For more than 14 years, we have been designing highly innovative vision systems for major clients with our most advanced technology to allow them to keep one step ahead with a lower risk. We are an outsourced R&D office for big companies.

# **CLIENTS**

























# R&D without risk

« To integrate a non mature but promissing technology in our system is always a risk. NEXVISION with its explorer temperament allows us to assess the viability of a new option by testing it themselves first. Then, we can be sure that what they propose is beyond the state of the art and functional. That really makes the difference.»

A helicopter manufacturer

# Time to market: to be the first

« We had a project that would have cost us 2 years of development. With NEXVISION expertise and agility, we gain a whole year of development, and a reduction of 50% of our cost. When you want to be the first on the market, NEXVISION is a major asset.»

A world leader in optronics for defense market

# Multiple high level expertises

« Optronic systems require multiple high level expertises for limited time. As NEXVISION masters the whole conception and integration chain, we know we can find what we need when we call them. »

A world leader in aerospace equipment

# **OUR PRODUCTS**

# A RANGE FOCUSSED ON SITUATIONAL AWARENESS

Nexvision also develops its own range of products centered on situational awareness. Designed mainly for defense and security applications, these products carry the best of our know-how and the latest technologies straight out of the laboratories

# Keywords:

- Night vision
- Panoramic vision
- Augmented reality
- Multispectral gyrostabilized gimbal
- Laser projector
- Sensor fusion



# A COMPLETE IMAGE PROCESSING & ANALYSIS ALGORITHM'S LIBRARY









**IMAGE CAPTURE** 

**OPTICAL** 

PRE PROCESSING

# MULTISPECTRAL IMAGE SENSORS

- > UV
- > Visible
- > Night vision
- > SWIR
- > LWIR / Thermal
- > TeraHertz

# OPTICAL ENHANCEMENT & CORRECTIONS

- > Super resolution
- > Aberration corrections
- > Chromatic aberrations
- > Relative illumination
- > Distorsion correction
- > Fisheye correction

# DECONVOLUTION

- > Image reconstitution
- > Recursive algorithms
- > Denoising
- > Myopic deconvolution
- > Lens defocused
- > Multi channels deconvolution

# **STABILIZATION**

- > Close control loop
- > Piezo actuator
- > Motion compensation
- > Viewer pointed

# IMAGE SENSOR PRE PROCESSING

- > CFA Bayer to RGB
- > Auto exposure
- > Multi resolution
- > Color matrix correction
- > Auto white balance
- > Gamma & YUV/HSI color conversion
- > Dead pixel correction
- > Non uniformity correction (FPN)
- > DSNU & PRNU
- > Anti flickering
- > Lab color space conversion
- > 2D Image scaling
- > 3D lookup table color correction
- > ACES color space management

**MISCELLANEOUS IP** 

- > Master AXI Lite Intf
- > AXI Lite Slave Intf
- > I2C driver

# **IP CORE FPGA**





### **ANALYSIS RESULTS**

⋺ ...

### **ENHANCEMENT**

### **ANALYSIS**

# DYNAMIC RANGE: HDR & NOISE FILTERING

- > High Dynamic Range
- > Dynamic local tone mapping
- > 3D noise filter
- > Contrasts & edges enhancement
- > Spatial filters

# **VIBRATION CORRECTION**

# **DETECTION / RECOGNITION**

### Methods

- > Feature extraction
- > Pattern matching
- > Texture recognition
- > Optical Character Recognition
- > Smart line detection (rail, lane, path, horizon)
- > Multispectral band object recognition
- > Content based image retrieval

### **Applications**

- > Suspicious stationary object detection
- > Motion detection
- > Number plate recognition
- > Traffic accident detection
- > Streetcar line detection
- > Fire detection
- > Pedestrian counting
- > Human body detection
- > Gesture recognition

### **TRACKING**

- > Online tracking
- > Specialized trackers
- > Autonomous tracking initialization

### **MACHINE LEARNING**

- > Shallow learning
- > Deep learning
- > Neural networks

### **ENVIRONMENT MEASUREMENT**

- > Augmented reality
- > SLAM
- > 3D scene reconstruction
- > Localisation / positioning
- > Advanced Driver Assistance System
- > Ground speed estimate
- > Unified scene alignment
- > Depth map
- > Sensors fusion
- > Barcode / QR Code reading
- > 1D, 2D, 3D measurement

### **DATA LINK**

### **VIDEO OUTPUT**

### 1/0

- > PCIe (FPGA Tegra DMA)
- > USB 2.0, 3.0 & 3.1
- > NVMe / SSD
- > Fiber-optic interconnect

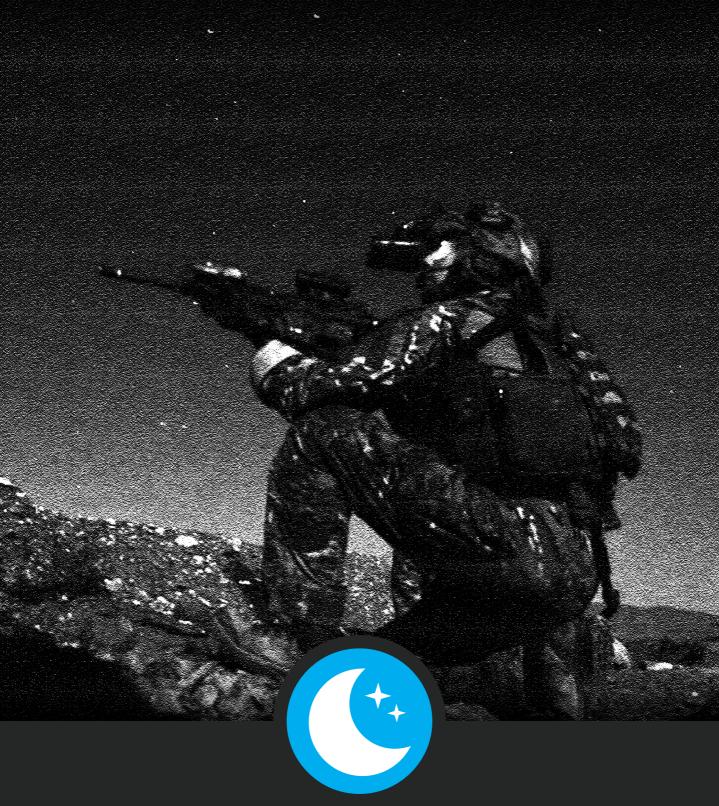
### 1/0

- > Composite
- > HDMI
- > SDI (3G-HD)
- > CoaXPress
- > Camera link

# **DISPLAY**

- > Microoled
- > LCD

- > SPI driver > Flash SPI
- > PWM



# ABOUT NIGHT VISION

To see by night is a relevant need in particular for special forces which operate by night and must take the advantage on the enemy thanks to technological solutions.

# NEXVISION OPTRONIC DESIGN

# NIGHT LEVELS



# **NIGHT VISION**

# WE OPERATE THREE MAIN NIGHT VISION SENSORS

NATO NIGHT LEVEL: up to 5

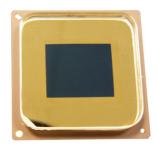
# S-CMOS SENSORS (LVL 3)



LYNX Black & white 1.3 Mpx



**KAMELEON** Color 1.3 Mpx



**EB-CMOS SENSOR (LVL 5)** 

**EBCMOS** Black & white 1.3 or 4.2 Mpx

# **PHOTONIS**







# **TECHNOLOGIES REVIEW**

Whereas the NVG (Night Vision Goggles) show their limits (weight, reduced field of view, analog image, weak resolution,...), new generation digital sensors make it possible to open a wide field of possibilities (better resolution, color, fusion of information, augmented reality, multi-spectral, noise filter, digital zoom, transmission, recording...).

# **ANALOG**

# Intensifier tube



### DIGITAL

CCD < EMCCD



CMOS < EBCMOS



# **ANALOG**

# Intensifier tube

- Low power consumption
- Low cost



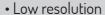


# DIGITAL

# CMOS - EBCMOS

- Sensitivity
- High resolution
- Color (S-CMOS)
- New applications thanks to embedded software
- Large field of view
- Possibility to separate sensor & display
- Consumption (EBCMOS)





- Reduced field of view
- No value added apps
- Monochrome





A RANGE OF SOLUTIONS FOCUSSED ON SITUATIONAL AWARENESS WITH TWO SPECIFIC EXPERTISES:

# **NIGHT VISION**



# **PANORAMIC VISION**



# SITUATIONAL AWARENESS?

### What is « situational awareness »?

It is an aid in the perception and awareness of an environment.

This includes a combination of three elements:

- Sensors with very wide fields of perception
- A sensor's information analysis algorithm
- A machine with a user-friendly and ergonomic interface presenting the results of these analyses.

# What is « situational awareness » for?

It allows a person to apprehend their immediate and surrounding environment, with a performance superior to that which their own senses can achieve in real-time, helping them to react and interact whilst performing a mission.

Furthermore, the «situational awareness» function of the machine is at the core of its autonomy during complex missions (i.e. autonomous land, air and sea vehicles, drones, robots working in outdoor environments etc.)

# What type of technology is necessary?

To get good perception in all types of extreme situations, a single type of sensor technology is not enough. The «situational awareness» function uses new types of miniaturized ultra-high-performance sensors (solid-state radar, active lidar / ToF depth camera imaging, night vision, throughfog imagers, thermal and near-infrared sensor, hyperspectral imagers, high-speed imagers) and sophisticated artificial intelligence analysis algorithm calculators (GPU/CPU, neural processor, FPGA).

# Why Nexvision got involved in « situational awareness »?

It was a natural progression. The intelligent perception of the environment is the technical basis of our market. With the rapid evolution in this type of technology, especially in terms of computing power, the possibilities today for applications based on vision systems are enormous and will only increase in the future. Over the course of our R & D projects, Nexvision has structured itself in such a way that we now have all the necessary skills in-house to build complex, tailor-made vision systems based on one or multiple image sensors whilst developing the entire system going with it; whether it be in electronic embedding (hardware, software - including image processing and analysis algorithms), but also optical and mechanical systems, with strong expertise in the fields of aeronautics, defense, security and transport.

# What are the key success factors?

Technical performance, quality assurance, ergonomics and price.

# How will this evolve in the years to come?

This will result in an explosion in the complexity and performance necessary for even more autonomous systems and robots; being that people will always seek to go faster and deal in more extreme conditions. Intelligent sensors for environment assessment must therefore follow this evolution; for without this, these robots will not be able to operate.

# **NEXVISION'S PRODUCTS ECOSYSTEM**



# **DEFENSE & SECURITY**



# A RANGE OF PRODUCTS FOR NEW BATTLE FIELD SITUATIONAL AWARENESS



# PORTABLE VIEWER



WE DESIGNED DIGITOWL, A PORTABLE DIGITAL SIGHT IMAGER THOUGHT ESPECIALLY FOR SPECIAL FORCES, THAT MATCHES LOW SIZE, WEIGHT, POWER AND COST (SWAP-C) CHARACTERISTICS. IN ADDITION, DIGITOWL IS ABLE TO EMBED VERY LOW LIGHT SENSOR (DOWN TO NATO LEVEL 5 WITH EBCMOS SENSOR FROM PHOTONIS).

# DIGITOWL

# PORTABLE HD DARK NIGHT SIGHT IMAGER

# NATO NIGHT LEVEL: 4 or 5

# **FEATURES**

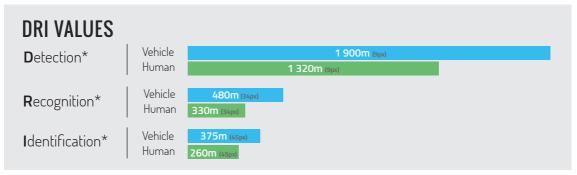
- Overcast starlight digital night vision (down to NATO level 5, down to 100µLux)
- Very high resolution: 7Mpixels, 4Mpixels (2K x 2K) or 2Mpixels (2K x 1K)
- Digital zoom x2, x4, x8
- Night Detection, Recognition, Identification
- Single-hand operation
- HD Microoled display

  Autogated
- --> Autonomy : 8 hours
- Digital video output: HD-SDI (SMPTE 292)



# SYSTEM CAPABILITY

- Adjustable display brightness
- Proximity sensor (display turns off when device is removed from the eyes)
- Digital zoom
- «Eventcheck» function to review last 30 seconds as video or image by image
- Positioning: geographic horizontal position (GPS latitude and longitude, date and time) and 3D orientation
- Menu to access system functions and settings
- Outgoing interface for wireless transfer of video



<u>\*About DRI</u> : Applying Johnson criteria to a high resolution sensor is not relevant. Since our sensor has 4 times the resolution, we define the DRI thresholds as indicated in the diagram. Calculating DigitOWL DRI values for a human according to Johnson criteria would result in D=5.2km (2.25pixels), R=1.3km (4.8pixels), I=1km (6.4pixels).



# APPLICATIONS

- Defense
  - → Special Forces
  - → Land / Naval / Air
- -- Customs
- -> Civil security



PRODUCT NAME	SPECIAL FEATURES
DigitOWL-EB4M « Essential »	EBCMOS intensified sensor from PHOTONIS Resolution : 4M pixel Spectral band : near infrared Night level sensitivity (NATO) : 5 ITAR
DigitOWL-EB2M « Essential »	EBCMOS intensified sensor from PHOTONIS Resolution : 2M pixel Spectral band : near infrared Night level sensitivity (NATO) : 5 ITAR
DigitOWL-IC7M « Essential »	iCMOS intensified sensor from PHOTONIS Resolution : 7M pixel Spectral band : near infrared Night level sensitivity (NATO) : 4 DUAL USE but export regulated : FOM > 1600)
DigitOWL-IC7M « Essential »	ITAR FREE iCMOS intensified sensor from PHOTONIS Resolution : 7M pixel Spectral band : near infrared Night level sensitivity (NATO) : 4 DUAL USE (ITAR FREE because FOM < 1600)
DigitOWL-VIS7M « Essential »	Color CMOS sensor from SONY Resolution : 7M pixel Spectral band : visible High dynamic range Night level sensitivity (NATO) : 2.5

OPTIONS		
« Extended »	GPS, Compass-IMU, distance evaluation reticule	
« LRF »	Laser range finder (3km range)	
« LWIR320 »	Thermal Infrared LWIR - Sensor: ULIS's ATT0320 - Fixed focal length	

ACCESSORIES		
Battery power pack	10 Ah	
Front protection optical filter	UV and NIR filter - scratch and water proof	



# PANORAMIC CAMERA



NEXVISION DESIGNED PANOMIX, A RUGGED PERIMETRIC SURVEILLANCE SYSTEM BASED ON A COMBINATION OF MULTIPLE 12MP COLOR SENSOR. ALSO AVAILABLE FOR NIGHT VISION WITH EBCMOS SENSOR.

# **PANOMIX**

# **ACCURATE SITUATIONAL AWARENESS**

# RUGGED PERIMETRIC SURVEILLANCE SYSTEM

# **FEATURES**

- 120° / 180° / 360° panoramic vision with realtime video stitching
- Customizable solution depending on vehicle constraints
- High performance video camera up to 72MP global shutter high sensitivity sensors
- Available with photonis EBCMOS sensor (night vision: down to level 5), up to 24MP
- Realtime intrusion detection and track following
- Fiber optic for long reach (up to 100m) uncompressed video transmission or wireless digital link for realtime H264 video streaming for drones
- Embedded inertial measurement unit for accurate video stabilization and worldspace measurement

# **ABOUT PANOMIX**

Panomix is a perimetric surveillance system based on a combination of multiple 12MP global shutter color sensor with very high sensitivity (down to NATO Night Level 2), a realtime panorama stitching system and a operating software for controlling, recording and playing back. Panomix is also available with EBCMOS sensor for night vision (down to NATO Level 5).

Panomix is available in numerous configuration customizable to fit the carrier, from two 180° modules, three 120° modules, or six 60° modules. Each module processes its own 9 axis inertial measurement unit.

It's weatherproof and waterproof (IP67) with "marine condition".

The marine casing is made to avoid reflecting radar echo wave (fit stealth mode requirement)

# **APPLICATIONS**

- → Surveillance
- Situational awareness
- → Defense
- Aerospace



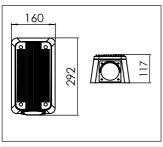




### ണ

60° / 120° / 180° / 360°



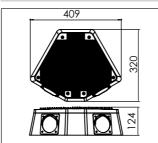


Weight: 5.5kg

### 120°

120°/360° (3x120°)



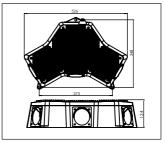


Weight : 9.5kg

### 180°

180° / 360° (2x180°)





Weight: 13.5kg

OPTIONS OPTIONS		
Мар	Geographical Information System (GIS) vectorized mapping on the Command Control software (C4-ISR)	
Sea ranging	Over the sea distance evaluation Passive/image processing based (no active imaging/ToF)	



# HEAD MOUNT DISPLAY



AUGMENTED REALITY AND FUSION, COMBINED WITH NIGHT VISION SENSORS AND IMAGE ANALYSIS.

# **EXTREM OWL**

# **COLOR NIGHT VISION SYSTEM FOR HELICOPTER PILOT HELMET** WITH AUGMENTED REALITY

# **FEATURES**

- KAMELEON sCMOS color night vision sensor
- Image projection on the visor thanks to micro-oled displays

- Stand alone helmet mounted display
  High resolution
  Wide field of view
  Clear picture of obstacles
  Good contrast
  Comfort of sight
  Compatibility with onboard avionics systems
  Security in flight conditions
  High dynamics

# **PHOTONIS KAMELEON SENSOR**

- Color
- sCM0S
- 1.3 Mpx



"A TREMENDOUS **COLOR VISION IN LOW LIGHT CONDITIONS!**"







# **NVS-11**

# NIGHT VISION SYSTEM FOR SPECIAL FORCES

# **AUGMENTED REALITY ON THE VISOR**

(data & multi image sensor fusion display)

# **FEATURES**

- Image projection on the visor thanks to micro-oled displays
- EBCMOS night vision sensor (NATO level 5)
- MWIR/Thermal sensor
- Augmented reality on the visor (data & multi image sensor fusion display)
- Mission-based symbology
- Human body detection, pattern matching, friends localization (to avoid blue on blue)
- Field of view > 80°
- Embedded image processing & analysis (Nvidia Tegra family GPU)
- Separate sensor & display => Removable tactical optronic (IR cam, wireless spy cam)
- Simultaneous Day/Night mode with the same sensor without interruption
- --- High resolution
- Best depth restitution Interoperability with C4-ISTAR
- System lighter than other existing systems :
  - Less than 700g on the helmet
  - Less than 1.5kg on the soldier, including batteries & processing unit
  - Standard helmet mount

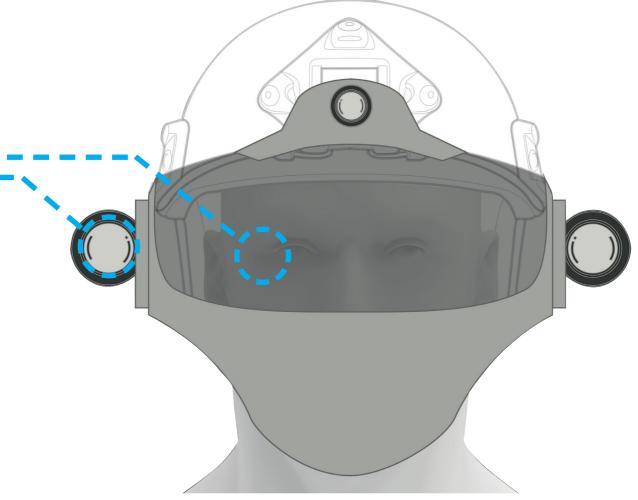
# **EBCMOS SENSOR**

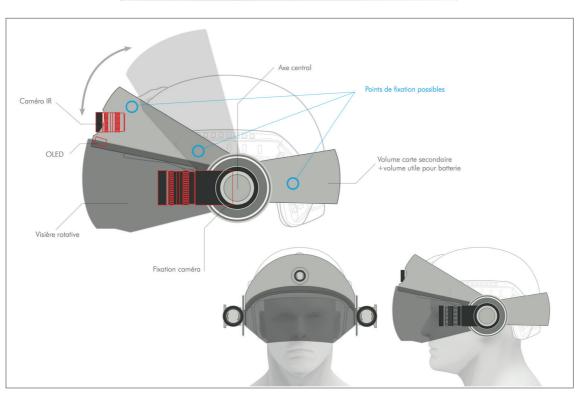
- Definition: 1.3Mpixel or 4Mpixel
- Black and white
- Sensitivity: 100µLux
- Automatic day night commutation
- Sensor cooling



# **R&D PROJECT**

**=** 







# GYRO POD



A RANGE OF GYROSTABILIZED GIMBALS FOR MANNED OR UNMANNED PLATFORM.

# **GSG-9 / GSG-11**

# LONG RANGE GYROSTABILIZED GIMBAL

# THE MOST POWERFUL POD OF THE MARKET!

# **FEATURES**

# For all manned or unmanned airborne platforms [ UAV, Helicopter..]

- Ultra HD 4K color & HD night vision [ starlight night level 4/5]
- → Dual spectral band long range zoom lens (40° to 2°): VIS & VNIR, 4K Ultra HD
- Huge image processing computing power (Al/deep learning processor)
- Ergonomic slaving to a high power laser searchlight
- Full 3D situational awareness, tracker
- Multispectral image sensor fusion
- → IP video & meta data streaming
- Embedded image analysis [target tracking, human body detection, vehicle pattern detection]
- --> Fast & accurate dual axis motorization (direct drive)
- -> Quick deployment & maintenance
- Low price, interoperability and flexibility of the solution, low logistic footprint

# Optional:

- SWIR, Thermal LWIR, MWIR with multispectral image sensor fusion
- Through fog active vision (range gated)
- Laser searchlight

# **APPLICATIONS**

- Surveillance (situational awareness)
- Research & tracking
- ---> Fire fighting
- Crisis management
- Protection of sensitives sites and events
- Law enforcement





# **MORE**

### Human machine interface control

[ by Extrem OWL: optical see through helmet mounted sight and display]





# **PAYLOAD SPECIFICATIONS**

# **SENSOR #1**: COLOR VISIBLE

7 Mpixel SONY-IMX420

• Resolution: 3208 x 2200

Pixel: 4.5µm

• Continuous optical zoom

• Fields of view : 2° to 40°

Magnification: x20

# SENSOR #2b : SWIR

• Resolution: 640 x 512

• Fields of view : 2° to 40°

• Magnification: x20

# SENSOR #3b : THERMAL LWIR 8-13pm

• Resolution: 640 x 480

Pixel: 12µm

• Fixed focal lens: 4°

# **SENSOR #2a**: NIGHT VISION

• 4 Mpixel EBCMOS PHOTONIS

Visible & near Infrared

• Continuous optical zoom

Fields of view : 2° to 40°

Magnification: x20

Sensitivity: 100µlux

# SENSOR #3a : THERMAL MWIR 3-5µm

Resolution: 1280 x 1024

Cooling by Stirling engine

Continuous optical zoom

Fields of view: 4° to 40°

Magnification: x10

\*Combination of : 1 + (2a or 2b) + (3a or 3b)

# GSG-9 • 11.7 kg / 25.8 lbs • 228mm (D) x 310 mm (H) • 9"(D) x 12.2"(H) • 18.2 kg / 40.1 lbs • 278mm (D) x 310 mm (H) • 11"(D) x 12.2"(H)

# **PANOSPOT**

# **ACCURATE SITUATIONAL AWARENESS**

# RUGGED PERIMETRIC & LONG RANGE ZOOM SURVEILLANCE SYSTEM

- 360° panoramic vision with realtime video stitching
- Panoramic view: darknight vision with 24Mpixel EBCMOS sensor + day vision with up to 72MP high sensitivity global shutter color sensor
- Pan tilt zoom narrow view : day color with 4K 8Mpixel sensor + through fog night vision with 4K 8Mpixel EBCMOS SWIR sensor
- Realtime intrusion detection and track following
- Fiber optic for long reach (up to 100m) uncompressed video transmission or wireless digital link for realtime H265 video streaming for drones
- Embedded inertial measurement unit for accurate video stabilization and worldspace measurement

# **CHARACTERISTICS**

# **TECHNICAL INFORMATION**

- A single fiber optic cable carries from one to three camera uncompressed video up to 100m distance. Fiber optics brings EMI and ground potential fluctuations immunity. The processing system fits in a 4U chassis.
- Power consumption for the camera is less than 40W
- 500W for the processing system

# **COMMUNICATION**

- Single 24-fiber optic cable with MTP connector per camera block (1 to 3 cameras per block)
- Up to 100m reach
- Hardened for harsh environments (Carlisle LITEAight HD cable)
- EMI and ground potential difference immune

# PROCESSING UNIT

 Depending on the needs of your application : could be a PC or an embedded solution based on FPGA and GPU.

# CAMERA HEAD UNIT POWER

- DC 10-28V
- Up to 15W per camera

# **APPLICATIONS**

- → Situational awareness
- Yacht / vessel protection
- Border / arbor surveillance
- → Vision based detection, point & tracking







# **ABOUT PANOSPOT**

Panospot is a perimetric surveillance system based on a combination of multiple 12MP global shutter color sensor with very high sensitivity (down to NATO Night Level 2) combined with multiple 4MP EBCMOS night vision sensor (NATO Night Level 5), a realtime panorama stitching system, a video analysis with a huge processing power to detect threads around and then spot-on with a Pan-Tilt-Zoom gyrostabilized pod, and a operating software for controlling, recording and playing back.

Panospot is available in numerous configurations customizable to fit the carrier. It's weatherproof and waterproof (IP67) with "marine condition".

# **PARTNERS**













# MOOVCAM



MOOVCAM IS A MODULAR VIDEO CAMERA WHICH HAS BEEN DESIGNED FOR MANY APPLICATIONS. IT ALLOWS TO CUSTOMIZE YOUR SIGHT VIEWER ACCORDING TO YOUR NEEDS (sensor, housing, I/O...)

### **MOOVCAM**

#### HIGH PERFORMANCE VIDEO CAMERA

#### A MODULAR CAM FOR MANY APPLICATIONS

#### **SENSORS**

- Visible (2M / 3M / 7M / 9M / 12M / 50M / 100M
- VNIR / Night (2M / 4M)
- S\\\/IR / FRS\\\/IF
- Thermal: MWIR (1.3M), LWIR (0.1M / 0.3M / 1.3M)

#### **OPTICS**

- Fixed focal
- Motorized zoom x20

#### Optic mount options

- C/CS
- Micro 4/3
- Canon EF-S

Mounting kit

Possibility to couple multiple Moovcam to enlarge the field of vision : 60° / 120° / 180° / 360° Stitching is done with our in-house algorithms.



#### HOUSING

- Industrial
- Marine
- Waternroof

Video Link Instant display (without storage)



- SDI
- Full HD
- 5 or 7 inches Black Magic

#### **VIDEO / DATA LINK**

#### I/O #1

- Fiber optic (PCle or direct)
- SDI (3G / 6G)
- CoaXPress (CxP3 / CxP6)

1/0 #2

USB

or

Camera Link

#### PC

Frame Grabber

Board

PCie switch

8 lanes or 4 lanes

with Fiber optic



#### CUSTOM EMBEDDED SYSTEM

Embedded Frame Grabber

(CamMaster 3D) Embedded VPU

Media SoC Nvidia / AM



0.3 0.2





### **MOOVCAM**

#### HIGH PERFORMANCE VIDEO CAMERA

#### **VERSIONS**

PRODUCT NAME	SPECIAL FEATURES	
VNIR Night vision : Photonis's EBCMOS/iCMOS		
MOOVCAM « EBCMOS 4M »	Spectral band : near infrared Sensor : PHOTONIS EBCMOS intensified Resolution : 4M pixel Night level sensitivity (NATO) : 5 Export regulation restriction	
MOOVCAM « EBCMOS 2M »	Spectral band : near infrared Sensor : PH0T0NIS EBCM0S intensified Resolution : 2M pixel Night level sensitivity (NAT0) : 5 Export regulation restriction	
MOOVCAM « iCMOS 12M »	Spectral band : near infrared Sensor : PHOTONIS iCMOS intensified Resolution : 12M pixel Night level sensitivity (NATO) : 4 Export regulation relaxed with FOM < 1600	
MOOVCAM « iCMOS 7M »	Spectral band : near infrared Sensor : PH0T0NIS iCM0S intensified Resolution : 7M pixel Night level sensitivity (NAT0) : 4 Export regulation relaxed with F0M < 1600	
MOOVCAM « iCMOS 3M »	Spectral band : near infrared Sensor : PHOTONIS iCMOS intensified Resolution : 3M pixel Night level sensitivity (NATO) : 4 Export regulation relaxed with FOM < 1600	

LWIR : ULIS's uncooled bolometer	
MOOVCAM « LWIR 320 »	Spectral band : Thermal Infrared LWIR Sensor : ULIS's ATT0320 Resolution : 320 x 240
MOOVCAM « LWIR 640 »	Spectral band : Thermal Infrared LWIR Sensor : ULIS's ATT0640 Resolution : 640 x 480

PRODUCT NAME	SPECIAL FEATURES	
SWIR : SOFRADIR's uncooled		
MOOVCAM « SWIR 640 »	Spectral band : Short Wave IR SWIR Sensor : SOFRADIR «SNAKE» Resolution : 640 x 512 ITAR	

	VISIBLE
MOOVCAM « <b>VIS7M</b> »	Spectral band : Visible, Color Sensor : SONY's «Pregius» global shutter IMX420 Resolution : 7M pixel High dynamic range Night level sensitivity (NATO) : 2.5
M00VCAM « <b>VIS12M253</b> »	Spectral band : Visible, Color Sensor : SONY's «Pregius» global shutter IMX253, 1.1inch Resolution : 12M pixel Night level sensitivity (NATO) : 2
M00VCAM « <b>VIS12M226</b> »	Spectral band : Visible, Color Sensor : SONY's «Starvis» IMX226, 1/1.7inch Resolution : 12M pixel
MOOVCAM « VIS4M »	Spectral band : Visible, Color Sensor : CMOSIS's CMV4000, 1inch Resolution : 4M pixel, 2000x2000

#### Interface choice

PCle over fiber optic link, 3G/6G-SDI output, USB link (type C connector), CameraLink

#### Frame grabber choice

Frame grabber PCle (4 or 8 channels fiber optics), USB link (4 channels), CameraLink

#### Lens mount choice

Micro 4/3 mount with motorized lens control link, CS type lens mount (C to CS adaptator)

### MOOVCAM « VIS12M253 »

#### HIGH PERFORMANCE VIDEO CAMERA

#### IDEAL FOR FAST MOVING OBJECT

#### **FEATURES**

- High performance video camera (4K 60fps)
- Perfect for fast moving object
- Fiber-optic allows a long distance remote head (useful in case of electromagnetic disturbance)
- Thanks to USB-C & PCle, MOOVCAM is one of the few video cam leveraging the full capacity of the SONY-IMX253 sensor
- Reduced housing

#### **APPLICATIONS**

- Machine vision (industrial)
- Traffic monitoring
- --> Broadcast / Cinema
- Defense
- Aerospace
- Surveillance (situational awareness) Submarine deep depth
- → Life science / Medical
- Microscopy

#### SONY-IMX253 SENSOR

- Global shutter
- Max **12.37Mp** 4/3 (4096 x 3000)
- 68fps (8 bit) / 64fps (10 bit) / 46fps (12 bit)
- 17.6mm diagonal (Type 1.1")
- 3.45µm square pixels



#### **PARTNERS**



























#### **OPTIONS**

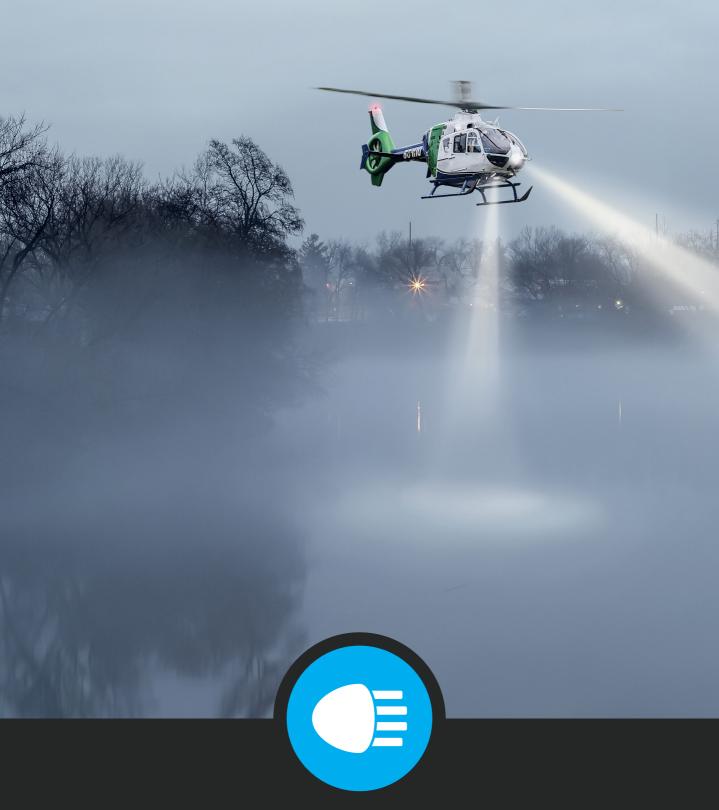
Processor : NVIDIA Tegra SOC Sensor : CMV50000 / CMV12000

Lens: Canon EF-S series

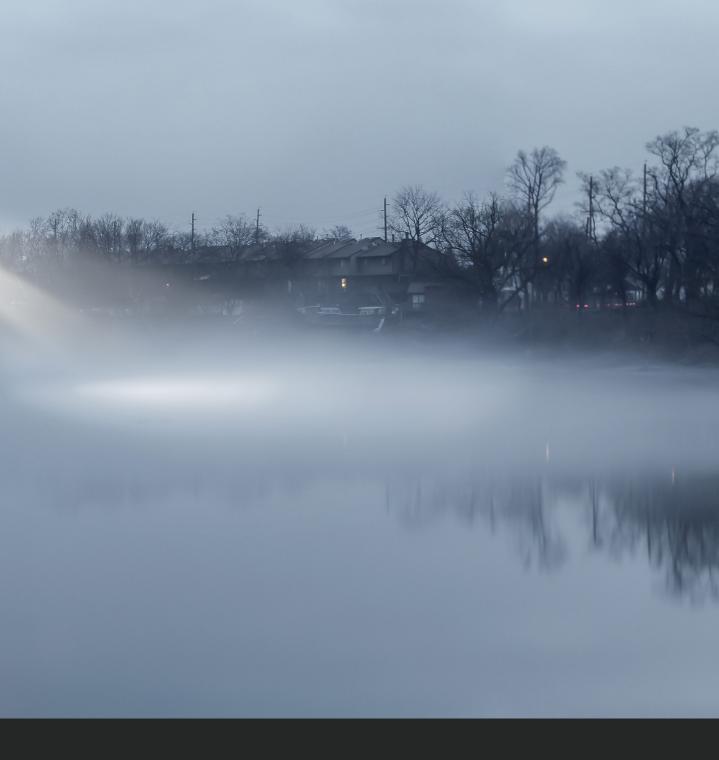








### SPOT LIGHT



A RANGE OF SPOTLIGHTS FOR DIFFERENT MISSIONS : TAKE OFF, LANDING, SEARCH & RESCUE AT NIGHT.

### **SLBS**

#### SCANNING LASER BEAM SEARCHLIGHT

#### **KEY FEATURES**

- --> High power RGB laser light source (80 000 lumen light output)
- Beam shape of any pattern of any RGB color mix at any point
- -- Long range lighting up to 3km
- Low power consumption <450W, low size 150mm diameter, low weight 9.5kg
- -> Very low aerodynamic drag
- Dimmable light power
- Range finder option
- Easy to install. Maintenance free.
- → Built-in tests (PBIT / CBIT)

#### **BENEFITS**

- Splitted light source and emitter head over fiber optic:
  - Laser light source can be ideally located close to electrical power source and cooling without being exposed to outdoors constraints
  - Projector head is compact, drastically reducing aerodynamic drag and associated consequences
- → High power RGB laser light source :
  - Compact, high efficiency
  - High speed and wide range power modulation of individual colors
- Compact X-Y high speed scanning mirror head:
  - Combined with laser sources modulation enables to draw a wide variety of beam shapes and sizes and even project basic color graphics
  - Enables much wider beam size modulation than conventional searchlight without any optics

#### **APPLICATIONS**

- -> Aerial work
- → Defense
- → Search & Rescue
- Enforcement

#### **SPECIFICATIONS**

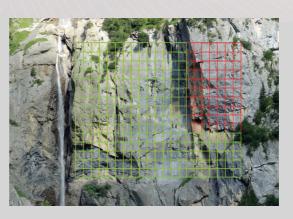
Beam-shape fan angle : 0.3° to 50°

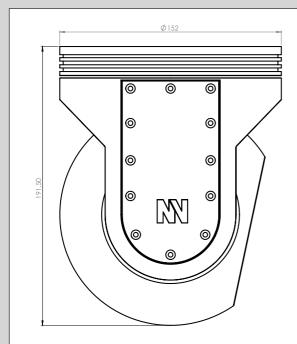
Gimbal steering:

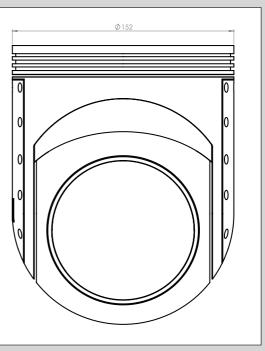
> Azimuth : +210° to -210° > Elevation : +20° to -180°











### **CLBS**

#### **COLOR LASER BEAM SEARCHLIGHT**

#### TAKE OFF, LANDING, SEARCH & RESCUE AT NIGHT

#### **KEY FEATURES**

- Laser lighting
- Spectral band R + G + B + optional SWIR
- Power output 160 to 30 000 lumen dimmable
- NightLight-Scotopic Luminous warm white flux (=RGB total)
- Working distance range: typical 2km. Range 0.1 (328ft) to 3km (~10kft) thanks to
- LASER's sustained beam coherency.
  Useful range for human target identification: typical 1km (~3.5kft)
- Beam-spot fan angle (paintbrush size): 4° to 15° variable

#### **BENEFITS**

- Splitted light source and emitter head over fiber optic :
  - Laser light source located close to electrical power source and cooling without being exposed to outdoors constraints
  - Projector head is compact, drastically reducing aerodynamic drag and associated consequences
- ++> High power RGB laser light source :
  - Compact, high efficiency
  - High speed and wide range power modulation of individual colors

#### **SPECIFICATIONS**

#### Searchlight head «SU»: gimbals subpart (outside aircraft)

- Envelope Size: Height 191.5mm (7.54"). Diameter: 150mm (5.9")
- Weight: 4.9kg (10.8lbs)
- Small ball design for a very low aerodynamic drag

#### Light beam generator & power supply subpart «PU» (inside aircraft)

- Main laser light generator
- Power supply to the searchlight head
- Size: Height 120mm (4.7"). Width: 200mm (7.9"). Length: 300mm (11.8")
- Weight: 3.9kg (8.6lbs)
- Heat dissipation : Active cooling with fan

#### User hand grip Remote Controler Unit «RCU» SUBPART (inside aircraft)

Size: Height 30mm (1.2"). Width: 120mm (4.7"). Length: 150mm (5.9")

- Weight: 0.7kg (1.5lbs)
- Night Vision Goggles (NVG) compatibility (MIL-STD-3009)

#### Control panel (joystick, buttons, display)

- A second user controler: panel version with extended features and more informative display
- Master/slave priority switch
- NVG compliant



#### **INSTALLATION KIT**

#### Mounted set: standard

- On fuselage head mounting enclosure
- default mounting option: easy to mount, certified and maintain.
- Height 230mm (9"). Width: 210mm (8.27"). Length: 210mm (8.27").

#### Takeoff-landing approach lighting

- Take-off and landing light
- 10000lumen LEDs
- 60° fixed beam angle
- · Available only on fuselage mounting set

#### Cables set: standard

- 1x PU <-> SU, 5m long (power supply «PU > SU» & high speed serial control link)
- 1 x PU <-> RCU, 10m long (power supply «PU > RCU» & control-command serial link)

#### Mounting custom set: brackets option

Side mounted on A/C

#### **OPTIONS**

- Slaving to electro-optics gyrostabilized gimbals (GSG9/11)
- Laser Near Infrared pointer (compatible with NVG devices)
- Laser Range Finder (eye safe SWIR, 1km range)
- LIDAR (high resolution 3D perception, «sense & avoid collision»)
- Thermal IR camera wide angle or narrow angle (LWIR)



# PROCESSING UNIT



FOR INNOVATIVE VISION SYSTEMS, YOU NEED HIGH COMPUTING POWER FOR IMAGE PROCESSING AND ANALYSIS.

SO, WE DESIGN CAM MASTER 3D : A POWERFUL PROCESSING PLATFORM READY-TO-CUSTOMIZE FOR HIGH-END EMBEDDED VISION SYSTEMS.

### **CAM MASTER 3D**

#### EMBEDDED VISION REFERENCE DESIGN BOARD

### A POWERFUL PLATFORM READY-TO-CUSTOMIZE FOR ROBOTIC APPLICATIONS

#### **OVERVIEW**

- --> Modular reference design
- Nexvision's most powerful computer vision unit for robotic market
- --> 2x NVIDIA® Jetson™ TX2 Module + FPGA video processing
- On-board video analytics (object tracking, deep learning)

#### **HIGHLIGHTS**

- On-board dedicated video enhancement image pipe (HDR, FPN, 3D noise reduction, HOG, stabilization), Nexvision's IP : NEXIP™
- Video: 3G-SDI in/out, HDMI output + optical fiber link (Quad Tx/Rx: up to 56 GT/s max, full duplex)
- Gigabit Ethernet, USB 3.1 Gen 1, SATA 2, SPI, I2C, PCle Gen 2
- Onboard video recording and meta data storage (SSD NVMe)
- ---> Onboard streaming server based on our NexStream™

#### **APPLICATIONS**



Robotics



Industrial inspection Machine vision



Deep learning for healthcare



Movie camera



Multispectral embedded vision systems



UAV – UGV – UUV



Situational awareness for autonomous vehicle

#### **PARTNERS**



















#### A PLATFORM WITH HIGH-END SOFTWARE LIBRARY

#### **IMAGE PROCESSING: NEXIPTM**

#### FPGA (Image Pre-Processing)

- Video enhancement and advanced video processing: temporal noise filtering and contrast enhancement
- Multiple exposure blending provides realtime HDR for high details retention in low and over exposed area
- Multispectral band image sensor fusion (Visible, SWIR, Thermal IR)
- · Feature point extraction, image stabilization, denoising

#### GPU (Image analysis and codec)

- Detection, recognition, tracking
- Machine learning / Al
- 3D perception / SLAM / 360° vision
- Full framerate, high quality video encoding

#### SOFTWARE DEVELOPMENT

#### Dedicated embedded Linux BSP based on buildroot, including:

- U-boot bootloader
- Custom Linux kernel based on NVIDIA® sources
- Integration of NVIDIA® Jetson<sup>™</sup> specific frameworks: CUDA®, OpenCV, OpenGL TensorRT<sup>™</sup>, cuDNN, NVIDIA DIGITS<sup>™</sup> Workflow, NVIDIA VisionWorks<sup>™</sup>, Camera Imaging, Video CODEC
- Customizable failsafe update system (FPGA, Software)
- Embedded debugging and profiling tools: quadd, nvprof, cuda-gdb, gdb, LTTng

#### External debugging and profiling tools:

Tegra system profiler, NVIDIA® NSight

#### Specific drivers:

• FPGA: PCle based, video acquisition, video display, Xilinx IPs (UART, SPI, I2C, XADC, ...), high speed inter SoCs communication channel, generic data transfer to/from SoC modules

#### **Nexvision's Middleware:**

- Video analysis framework
- Embedded video recording: H264, H265, MP4, MKV, AAC
- Video streaming: RTSP/RTCP/RTP, H264, H265, AAC
- ONVIF NVT profile support

### **CAM MASTER 3D**

#### EMBEDDED VISION REFERENCE DESIGN BOARD

#### **SYSTEM SPECIFICATIONS**

#### MAIN BOARD (PRE PROCESSING + I/O)

#### Front-end image processor (FPGA)

Xilinx Kintex Ultrascale (KU025 / 035 / 040 / 060 / 095) or Ultrascale + (KU11P or KU15P)

#### One configuration memory

- 512 Mb NOR flash
- R/W access via SoC (over-the-air update via Ethernet)

#### Memory banks on FPGA

- Up to 2x 512MB 16-bit DDR4@2400Mb/s (6.4 GB/s)
- Up to 2x1GB 32-bit DDR4@2400 Mb/s (19.2 GB/s)

#### **EEPROM** storage

1x I2C 128 kb EEPROM

#### **Development tools**

- 8-bit dedicated I/O (DSIO) LVCMOS 3.30V to FPGA
- 1x JTAG port for FPGA configuration
- 2x LED for FPGA

#### **Environment management**

- 4x temperature sensors
- 1x FAN drive by PWM 12V
- Inertial sensors (3D acceleratometer, 3D gyroscope, 3D magnetometer)

#### **ONE MAIN HOST INTERFACE**

- PCI Express
  - o 1x PCle Gen3 x8
  - o 1x PCle Gen3 x4
- 12V and 3.30V Input supply voltage (75 W max)
- LVDS and LVCMOS (3.30 V)

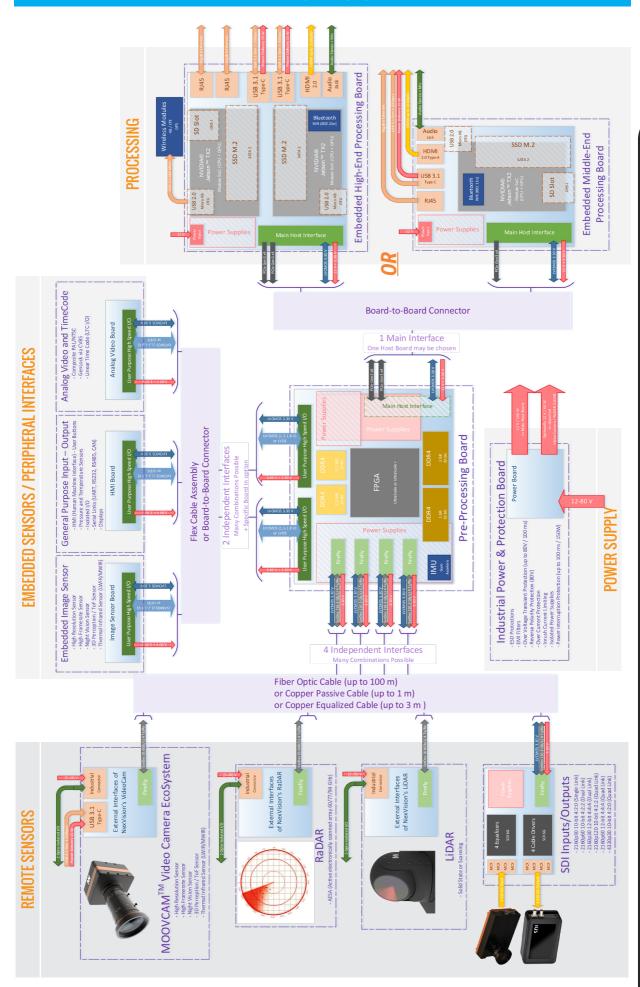
#### UP TO 4x FIREFLY INTERFACE [Serial high speed]

- 4 Lanes SerDes full duplex
  - Up to 16.6 GT/s per lane
- Provide 3.30V supply voltage
- 8x LVCMOS 3.30V control I/O
- Copper (short distance) or Fiber (long distance)

### UP TO 2x INDEPENDANT USER PURPOSE INTERFACE [ Parallel high speed and low speed ]

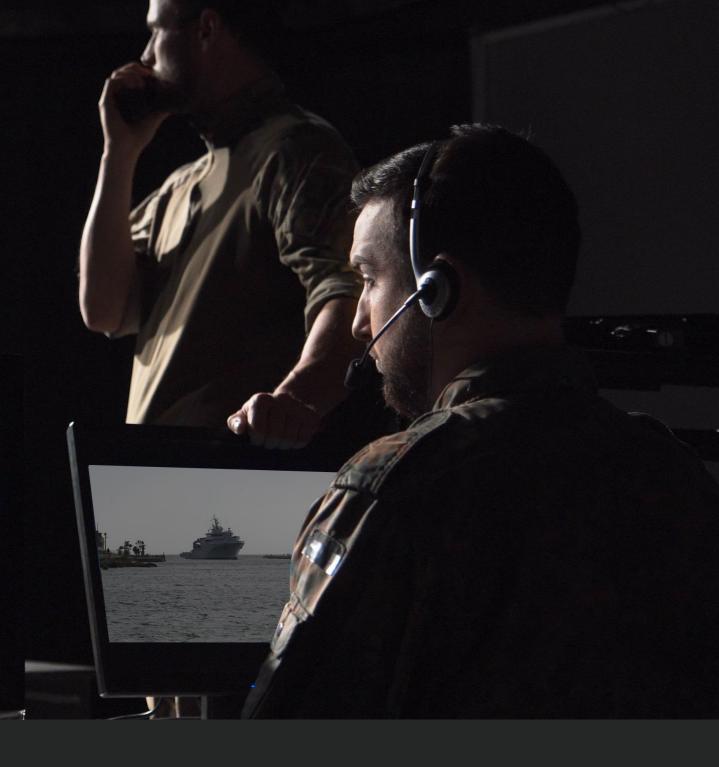
- Board-to-Board interface or flex cable
- Provide main 3.60V supply voltage and low power 3.30V voltage
- Level voltage signalling referenced by the targeted board, support :
  - Up to 24 LVDS pairs
  - Oup to 52 LVCMOS flexible (1.20-1.80 V)
  - Up to 18 LVMCOS fixed 3.30V

#### **ARCHITECTURE**





VMS C4-ISR



VMS IS OUR HOME-MADE VIDEO MANAGEMENT SYSTEM.
MADE OF DIFFERENT TECHNICAL BRICKS, IT ALLOWS
SEVERAL CONFIGURATIONS, DEPENDING ON THE GLOBAL
SURVEILLANCE MONITORING CENTER.

### **NEXVMS**

#### COMMAND & CONTROL CENTER (Safety & Security)

### SURVEILLANCE MONITORING CENTER, COORDINATION OFFICE & VIDEO CAMERA SUPERVISION

#### FOR:

- Defense (C4-ISR)
- Government
- Border police
- Coast guards
- Companies

#### PROTECTION OF :

- Cities (smart cities)
- Borders
- Maritime area
- Critical infrastructures
- Sensitive areas (SEVESO sites, banks, casinos, airports, military installation...)
- Onboard surveillance (aircrafts, vessels, train, tramway, bus...)

#### **VERSIONS:**

- City
- Airborne
- Marine vessel
- Cross-platform

#### **USE CASES**



#### A380 CABIN VIDEO MANAGEMENT SYSTEM

- 30 cabin video camera
- · Display adaptater unit
- · Crew monitoring display
- · Remote monitoring display
- Ground monitoring display
- DVR (recorder)
- · Display cockpit



#### **FES CITY CCTV**

- 300 HD video camera
- · Wireless connection
- 25 monitoring screens
- Complete city map
- · Redundancy for video storage
- · Customized survey scenario
- Personal privacy protection
- 24/7

« Only 5 months after the beginning of deployment, the systems allowed 30 police interventions by day, increasing the security of all the town, for both citizens and tourists. »

#### **NexCAM Smart™**

#### 1 to 10 Mpixel Network Video Camera

- Visible HD with and without HDR
- Night vision
- SWIR
- LWIR / Thermal
- Terahertz



#### NexRMC™

#### Remote Media Control Software

- High quality video & audio streaming
- Recording, digital I/O, PTZ control
- Ergonomic & intuituve interface
- Protocols & compatibility



#### NexNVR™

#### Network Video Server & Recorder

- Over IP Network
- Integrated automatism
- Low power RF link, Zigbee compliant
- · Database security
- image watermarking on demand
- · Data encryption on demand

#### **CLASSPATH**

#### Software Modular Architecture

- RTSP/HTTP/SFTP Client & Server
- Compression
- Ternary search tree
- File storage
- File format
- Cryptographic primitives
- Database
- Encoding
- Network
- Streaming
- Licensing
- · Multi threading

#### NexMAP™

### Human Interface Monitoring on geotagged GIS map

• Manages specific types of geographically referenced data with object management.



#### NexIO™

### Automation, Access control & audio on IP network

- Autonomous audio/ video security network controller
- IP PLC
- Connected home
- Urban automation



#### NexSETUP™

### Allows configuration of sources, recording-schedules, users and configuration of NVRs

- Video source setup
- · Source-group setup
- · Video recording setup
- NVR setup
- User setup
- NEXIO setup

#### NexIP™

### Powerful image processing & analysis algorithms library

- Optical enhancement, deconvolution, stabilization, pre processing, HDR & noise filtering
- Detection, recognition, Tracking
- Machine learning
- Environment measurement





## OUR QUALITY MANAGEMENT SYSTEM

The purpose of the Nexvision Quality Management System (NV QMS) is to assure the business through excellent products which fully satisfy or exceed customer expectations and user requirements. Quality Management Principles are:

- ---> Customer focus
- Leadership
- Involvement of people
- Process approach

In order to develop safe systems within short delay, adapted, agile methods are applied in management and development. The applied methods are scrum and Agile Systems Engineering (ASE). For quality processes, this means that:

- A major part of the continuous improval is simplification wherever possible
- Any rule which does not fulfil its purpose will be modified immediately.

The NV QMS is based on the requirements of the international standards ISO 9001:2015 and EN 9100:2016. This system addresses the design, development and production of the company's products. Identifying, understanding, and managing interrelated processes as a system contribute to the organization's effectiveness and efficiency in achieving its objectives.

#### **INFRASTRUCTURE**

To meet quality objectives and product requirements Nexvision has determined the infrastructure needed. The infrastructure has been provided, and includes workspace, utilities, process equipment and supporting services. As new infrastructure requirements arise, they will be documented. Existing infrastructure is maintained to ensure product conformity.

### EQUIPMENT MONITORING & MEASUREMENT

All measuring and test equipment used for verification of products is calibrated using calibration standards traceable to the national standard. Calibration records are maintained. The calibration status of measuring equipment is identified with calibration stickers. The equipment is well maintained and its placement and use are controlled.

#### **DESIGN & DEVELOPMENT**

Design activities are defined with their milestones and reviews that are required to ensure a good design every time. In addition, responsibilities and means for requirements traceability and design approval are assigned. This process defines also how design changes are controlled and approved. Depending on the project and on customer requirements, different standard documents are applied. Current experience includes for example:

- MIL-STD-785B, MIL-STD-810
- STANAG 4370
- ARP4754a
- RTCA DO 160 / Eurocae ED-14
- RTCA DO 178 / Eurocae ED-12
- RTCA DO 254 / Eurocae ED-80

The development cycle will always be adapted to the scope and context of each project. Using existing Nexvision modules, the time to market is reduced significantly with respect to the classical process.

"The Nexvision Quality Management System is based on the requirements of the international standards ISO 9001:2015 and EN 9100:2016."







