



# eVPU - Embedded Vision Processing Unit

Powerful computing platform for image processing and analysis

**UP TO 32x 4K CAMERAS**

100Top/s - 100Gb/s data stream - 100w





# A POWERFUL EMBEDDED CALCULATOR FOR SITUATIONAL AWARENESS



Tank/train/bus/trucks/UGV  
Unmanned Ground Vehicle



Autonomous tractor  
Smart Farming



RPAS/UAV  
Unmanned Aerial Vehicle



AUV  
Autonomous Underwater Vehicle



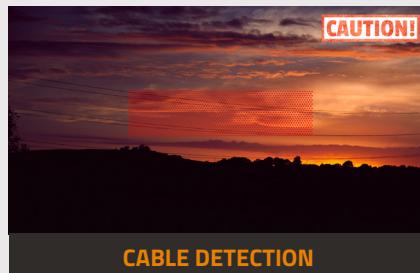
USV  
Unmanned Surface Vessel



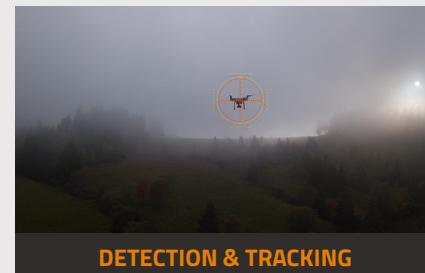
Aircraft/VTOL  
Vertical Take off & Landing

## EVS/EFVS (Enhanced Vision System/ Enhanced Flight Vision System)

For vehicle, autonomous or not, in extreme conditions [#DVE - Degraded Visual Environment]



CABLE DETECTION



DETECTION & TRACKING



THREAT IDENTIFICATION



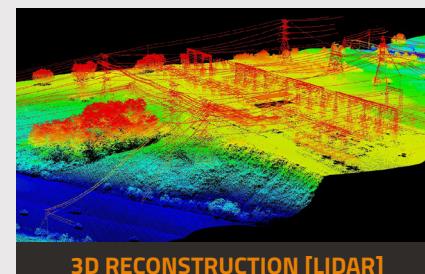
PATH PLANNING



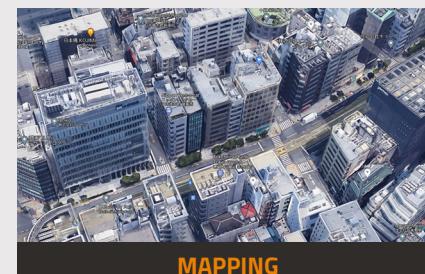
SEARCH & RESCUE



INFORMATION PROJECTION



3D RECONSTRUCTION [LIDAR]



MAPPING

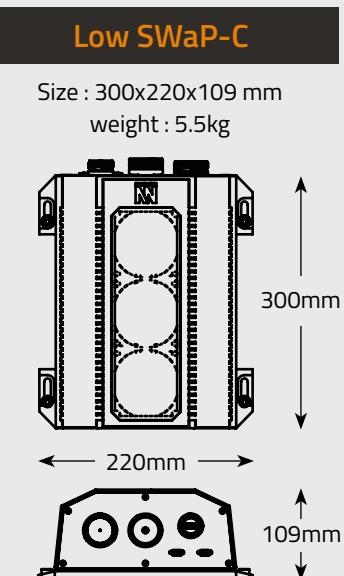


Image analysis through embedded GPU + Neuronal network (object detection & tracking, deep learning)



NVIDIA<sup>®</sup>  
Jetson AGX Xavier™



XILINX<sup>®</sup>  
Ultrascale+ FPGA

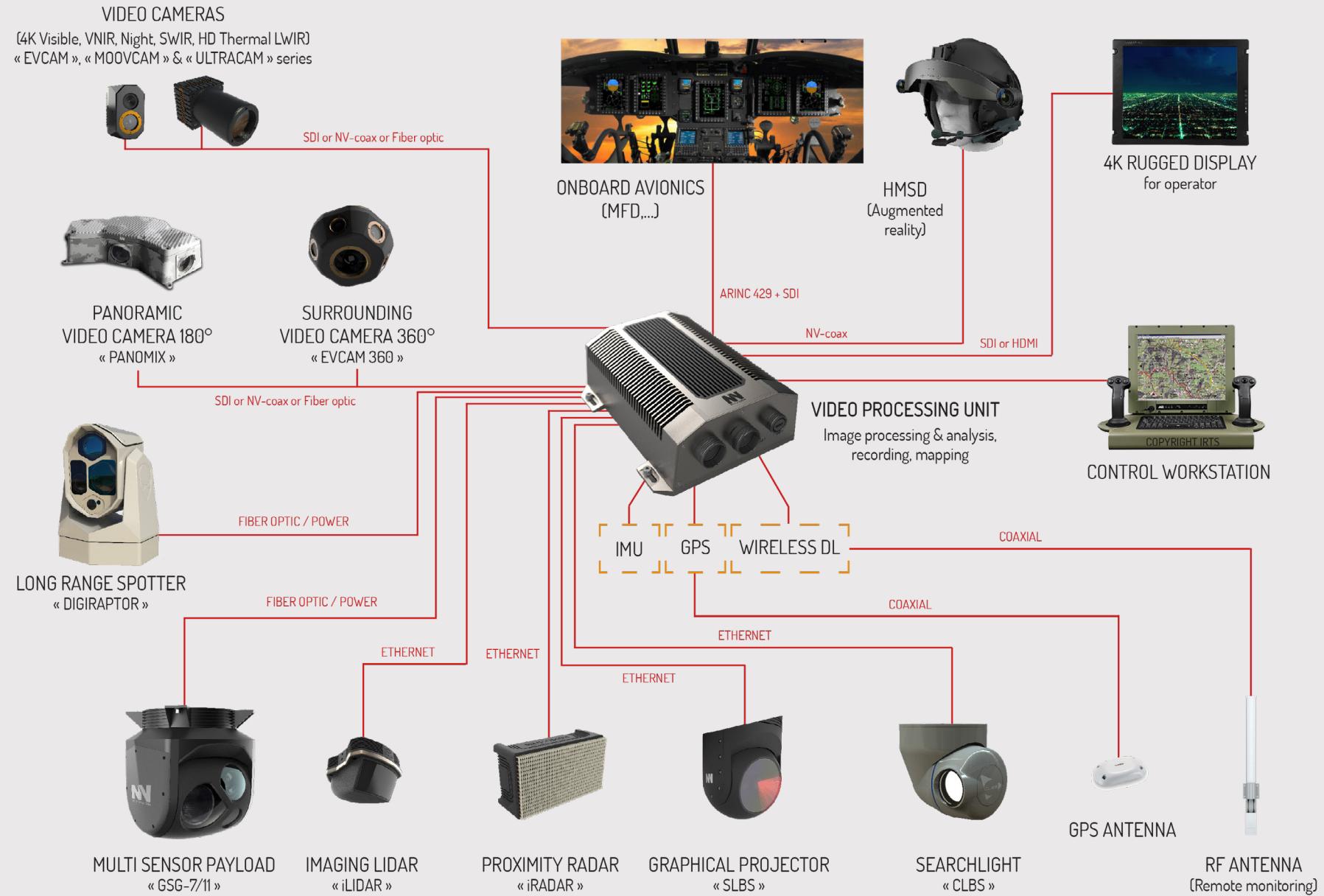


POWERED  
BY ARM



**COMPATIBLE WITH ALL NEXVISION' SENSORS & ALL DEVICES OF THE MARKET :**  
*Video camera in Visible, Infrared night vision (VNIR, SWIR, thermal MWIR/LWIR) or Active 3D LiDaR/RaDaR*

**Perfect for data fusion, image processing and analysis (detection, tracking...)**



# VIDEO PROCESSING PERFORMANCE

## Front-End Image Co-processor (FPGA)

- 650k logic elements
- 22 Mb SRAM
- 3x 1GB DDR4 @2666 Mb/s (42.66Gb/s)
- 512 Mb NOR Data Flash

## System on Chip GPU modules

Up to 3x onboard parallel NVIDIA® Jetson AGX Xavier™ Module.  
Each SoC has the following performance :

CPU	CPU 8-core Carmel ARM v8.2 64-bit CPU, 8MB L2 + 4MB L3
GPU	GPU 512-core Volta GPU with 64 Tensor Cores 11 TFLOPS (FP16) 22 TOPS (INT8)
AI performance	32 TOPs DL Accelerator (2x) NVDLA Engines*   5 TFLOPS (FP16), 10 TOPS (INT8)
Vision accelerator	7-way VLIW Vision Processor
Video capabilities	<p><b>Video Encode</b> 2x1000MP/sec 4x 4K @ 60 (HEVC) / 8x 4K @ 30 (HEVC) 16x 1080p @ 60 (HEVC) / 32x 1080p @ 30 (HEVC)</p> <p><b>Video Decode</b> 2x1500MP/sec 2x 8K @ 30 (HEVC) / 6x 4K @ 60 (HEVC) 12x 4K @ 30 (HEVC) / 26x 1080p @ 60 (HEVC) 52x 1080p @ 30 (HEVC) / 30x 1080p @ 30 (H.264)</p>
Embedded memory	32GB 256-Bit LPDDR4x   136.5GB/s
Embedded storage	32GB eMMC 5.1
FPGA link	PCIe Gen 3 1x SoC with 8 lanes and 2x SoC with 4 lanes

# I/O

## VIDEO INPUTS

### 12x Digital (mix of the following type of links)

- **Optical fiber** (proprietary fiber optic protocol)  
> 16 Gb/s per lane [0 ; 70] °C  
> 10.3 Gb/s per lane [-40 ; +85] °C
- **SDI** 12G/6G/3G
- **NV-COAX** up to 16 Gbit/s Down Link + camera control Up Link + 20w power-over-coax

## VIDEO OUTPUTS

### Digital

- **12x SDI** 12G/6G/3G
- **1x HDMI** 4096x2160 at 60 Hz

### Analog

- **2x Composite PAL/NTSC** (CVBS)
- Optional : **2x STANAG 3350** Class B

## DATA LINK

### USB

- **USB 3.1** type C connector

### Ethernet

- **2x Ethernet Gigabit** Slot M12 (1000 BASE-T)
- 1x Ethernet Gigabit **switch**

### Serial

- **4x RS485/422**
- Optional : **ARINC 429** 8x IN / 6x OUT (100 kb/s)

## STORAGE

### SSD

- **2x SSD NVMe** up to 10 TB

### EEPROM

- 1x 2Mb EEPROM per SoC
- 1x 2Mb EEPROM for FPGA

## OTHERS

### Discrete I/O

- 4x protected I/O 28V

### Temperature management

- Airflow cooling

# ENVIRONMENT

MIL-STD 810G compliant

- Operating temperature Range : -20°C to 70°C
- Humidity : 10-90% non condensing

# POWER SUPPLY

MIL-STD 1275B compliant

Voltage range	9-36 V <sub>DC</sub>
Power consumption	
▪ Light process > 1 SoC (40% Load) > Ambient temp : 25°C	35W
▪ Typical application > 2 SoC (70% Load) > Ambient temp : 55°C	75W
▪ Peak process > 3 SoC (100% Load) > Ambient temp : 70°C	120W



## IMAGE PROCESSING : NEXIP™

### FPGA (Image Pre-Processing)

- Video enhancement and advanced video processing : Temporal noise filtering and contrast enhancement
- Multiple exposure blending provides realtime HDR for high details retention in low and over exposed area
- Multispectral band image sensor fusion (Visible, SWIR, Thermal IR)
- Feature point extraction, image stabilization, denoising

### GPU (Image analysis and codec)

- Object detection, recognition, tracking
- Machine learning / AI / Pattern matching
- 3D perception / SLAM / 360° vision (stitching)
- Full framerate, 4K high quality video encoding

## SOFTWARE DEVELOPMENT

### Dedicated Embedded Linux BSP based on Buildroot, including:

- U-boot bootloader
- Custom Linux kernel based on NVIDIA sources
- Integration of NVidia Tegra specific frameworks: CUDA®, OpenCV, OpenGL TensorRT™, cuDNN, NVIDIA DIGITS™ Workflow, NVIDIA VisionWorks™, Camera Imaging, Video CODEC.
- Customizable failsafe update system (FPGA, Software)
- Embedded debugging and profiling tools: quadd, nvprof, cuda-gdb, gdb, LTTng

### External debugging and profiling tools:

- Tegra system profiler, NVIDIA NSight

### Specific drivers:

- FPGA: PCIe based, video acquisition, video display, Xilinx IPs (UART, SPI, I2C, XADC, ...), High Speed Inter SoCs communication channel, generic data transfer to/from SoC modules
- Arinc 429: network socket interface based, label filtering, high/low speed configuration, multi-channel support

### Nexvision's Middleware:

- Video Analysis Framework
- Embedded Video Recording: H264, H265, MP4, MKV, AAC
- Video streaming: RTSP/RTCP/RTP, H264, H265, AAC

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